

IRA Code Design for Iterative Detection and Decoding: A Setpoint-based Approach

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Abstract—In this paper, a novel setpoint-based design approach for Irregular Repeat Accumulate (IRA) codes in iterative detection and decoding structures is presented. In contrast to conventional IRA code design in which the convolutional decoder is combined with the detector, the goal behind this approach is to keep the IRA decoding structure consisting of convolutional decoder and repetition decoder intact, i.e. to consider it as an inner loop of the overall detection structure. The outer loop is then composed of the IRA decoder and the system specific detector. This approach requires to adapt the irregular repetition code jointly to the convolutional decoder as well as to the detector which is achieved by formulating setpoints for the inner and outer code characteristic. As will be shown, the presented code design approach, although starting from a completely different viewpoint as the conventional approach, leads to an irregular repetition code with a very similar transfer characteristic and code rate than the conventional approach.

I. INTRODUCTION

In 1993, Berrou, Glavieux and Thitimajshima published their work on a class of what they called turbo-codes [1]. Due to the concatenation of simple component codes connected via interleavers they achieved error-free transmission near the capacity limit while still allowing decoding at reasonable effort. Divsalar et. al. presented a generalization of turbo-codes with what they called repeat-accumulate (RA) codes [2] consisting of a serial concatenation of an outer repetition code and an inner accumulator. Like turbo-codes, RA codes offer a linear encoding complexity and allow an efficient decoding based on belief propagation. In [3] Jin et. al. generalized RA codes to so-called Irregular Repeat-Accumulate (IRA) codes applying a mixture of repetition codes of different code rates as outer component code. Due to this code mixture, IRA codes offer higher degrees of freedom than regular RA codes, making them an interesting candidate for various applications.

A particular interesting field of application for IRA codes are iterative detection schemes found in Multiple-Input Multiple-Output (MIMO)- or in Multi-User-Detection (MUD) systems. In such systems, code design requires thorough adaption of the code parameters to the overall detector, e.g. a sphere decoder in MIMO systems or a soft-RAKE detector in Interleave-Division Multiple-Access (IDMA) systems [10].

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Both detectors realize a sub-optimal implementation of the maximum a-posteriori-probability (MAP) detector. For IRA codes this means, that the irregular repetition code needs to be adapted to the convolutional decoder as well as to the detector at the desired working point.

In [4], ten Brink and Kramer presented a general design approach for IRA codes in the context of iterative detection systems. There, they combined the detector with the convolutional decoder to an inner entity whose transfer characteristic was determined by EXIT-analysis [5]. The degree distribution of the irregular repetition code was then found by matching the EXIT-curve of the irregular repetition code to the EXIT-curve of the inner entity. This methodology was adapted successfully for IDMA-based multi-user systems, e.g., in [6] and later in [7].

Despite the success of the aforementioned approach it seems more intuitive to keep the decoding structure of the IRA code consisting of convolutional decoder and repetition decoder intact, i.e. to treat the IRA decoder as inner entity. However, doing so requires to adapt the repetition code jointly to the convolutional decoder as well as to the detector. The goal is then to end up with an IRA code that fulfills the following two properties:

- 1) in the beginning of the iterative detection process, the code should only slightly improve the overall detection with every outer iteration. It should not instantly lead to a perfect decoding as this would implicitly mean a rate loss.
- 2) towards the end of the iterative detection process, i.e. with sufficient information from the detector, the code should allow perfect decoding.

In the following, we present a design approach for IRA codes in the context of iterative detection schemes which treats the IRA decoder as inner entity and allows to design the code such that the two aforementioned properties are fulfilled. Hereby, we focus on non-systematic IRA codes as in [4] which can perform as well as systematic IRA codes while simplifying the design process, since the repetition decoder only receives information from the convolutional decoder and not from the detector. In order to optimize the repetition code jointly to the detector and the convolutional decoder, a desired outer code characteristic is formulated which is matched to the detector. From this desired characteristic a set of setpoints is determined which the code has to achieve. Translating these setpoints to

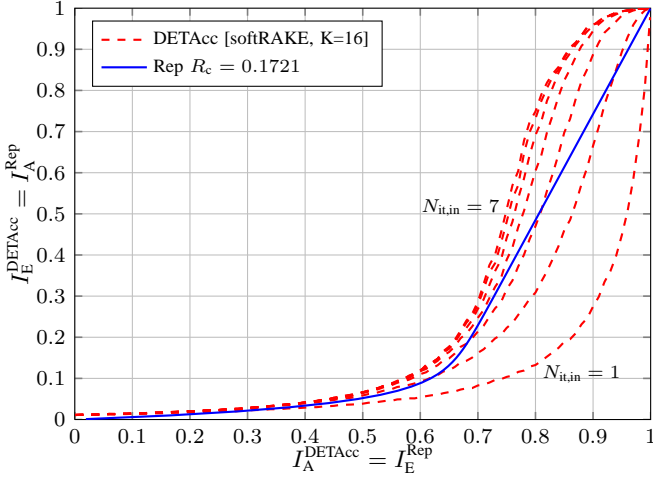


Fig. 3. Transfer characteristic of inner entity DETAcc consisting of detector and convolutional decoder for different numbers of inner iterations and optimized irregular repetition code. As example for the detector a soft-RAKE detector [10] for $K = 16$ layers over an AWGN channel at $1/\sigma_n^2 = 5$ dB is chosen.

of the inner loop is given for different numbers of inner iterations $N_{it,in}$. I_A^{DETAcc} hereby denotes the a-priori information which is fed back from the repetition decoder \mathcal{D}_{Rep} and σ_n^2 is the noise variance on the channel, i.e. the working point of the system. As can be seen from the figure, the transfer characteristic of the inner entity does not change significantly anymore after $N_{it,in} = 5$ inner iterations. Hence, $N_{it,in} = 5$ inner iterations are sufficient and the irregular repetition code should be adapted to this transfer characteristic.

The overall transfer characteristic T^{Rep} of the irregular repetition code is given by

$$I_E^{Rep} = T^{Rep}(I_A^{Rep}) = \sum_{\rho=\rho_{min}}^{\rho_{max}} w_{\rho} I_{E,\rho}^{Rep}, \quad (2)$$

where

$$I_{E,\rho}^{Rep} = T_{\rho}^{Rep}(I_{A,\rho}^{Rep}, \rho) \quad (3)$$

is the regular repetition code of code rate $R_c = \frac{1}{\rho}$ and $0 \leq w_{\rho} \leq 1$ is its weight in the code mixture. Here, ρ_{min} and ρ_{max} are design parameters limiting the minimal and maximal repetition factors in order to, e.g., control the error-floor behaviour of the code [8].

The transfer characteristic of the repetition code can be described analytically as

$$I_{E,\rho}^{Rep} = T_{\rho}^{Rep}(I_{A,\rho}^{Rep}, \rho) = \mathcal{J}\left((\rho - 1) \mathcal{J}^{-1}\left(I_{A,\rho}^{Rep}\right)\right) \quad (4)$$

with

$$\mathcal{J}(\nu) = \left(1 - 2^{-1.0605\nu^{0.8935}}\right)^{1.1064} \quad (5a)$$

$$\mathcal{J}^{-1}(\nu) = \left(-1/1.0605 \log_2(1 - \nu^{1/1.1064})\right)^{1/0.8935} \quad (5b)$$

denoting the J-function and its inverse.

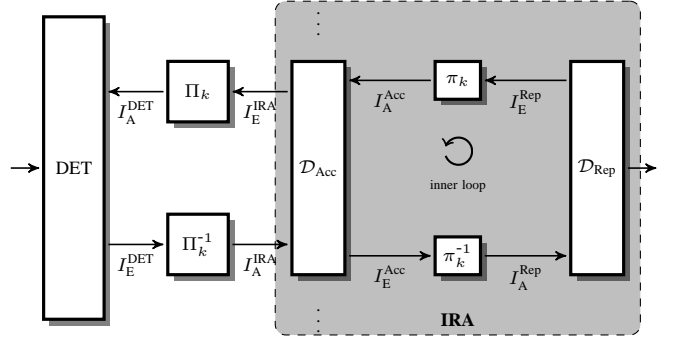


Fig. 4. Novel approach: iterative receiver combining convolutional decoder and repetition decoder to inner entity; irregular repetition code is adapted jointly to detector as well as convolutional decoder.

The goal is now to match the transfer characteristic I_E^{Rep} of the irregular repetition code to match the characteristic I_A^{DETAcc} of the inner entity by adapting the weights w_{ρ} , i.e. to solve

$$[w_{\rho_{min}}, \dots, w_{\rho_{max}}] = \arg \min \left\{ I_E^{Rep} - I_A^{DETAcc} + \Delta \right\} \quad (6a)$$

$$\text{s.t.} \quad \sum_{\rho=\rho_{min}}^{\rho_{max}} w_{\rho} = 1 \quad (6b)$$

$$I_E^{Rep} > I_A^{DETAcc}, \quad (6c)$$

where Δ is the minimal allowed gap between both transfer curves and mainly determines the number of required iterations to achieve convergence.

The characteristic of the resulting irregular repetition code is depicted as well in Fig. 3. The code matches the characteristic of the inner entity very well up to approx. $I_E^{DETAcc} = 0.4$. Above this point, the s-curve behaviour of the inner entity which is mainly caused by the accumulator does not allow a perfect adaption of the repetition code. The coderate of the resulting overall code in this example is $R_c = 0.1721$.

B. Setpoint-based approach

A different approach aims at keeping the original decoding structure consisting of convolutional decoder and repetition decoder intact, i.e. performing the inner iterations between convolutional decoder and repetition decoder as depicted in Fig. 4. The outer iterations are then performed between the inner entity, i.e. the IRA channel decoder, and the detector. Since the irregular repetition code has to be adapted to both, the detector as well as the convolutional decoder, the inner, as well as the outer IRA code characteristic have to be considered in the design process.

1) *Outer code behaviour:* As a starting point, the desired outer IRA transfer characteristic

$$\bar{I}_E^{IRA} = T^{IRA,out}(I_A^{IRA}) \quad (7)$$

is formulated. It should be adapted to the transfer characteristic $I_E^{DET} = T^{DET}(I_A^{DET}, \sigma_n^2)$ of the detector at the given working point σ_n^2 . Since the IRA code should match the detector as well as possible, the desired code characteristic is just set as the detector's characteristic with a fixed gap of Δ as

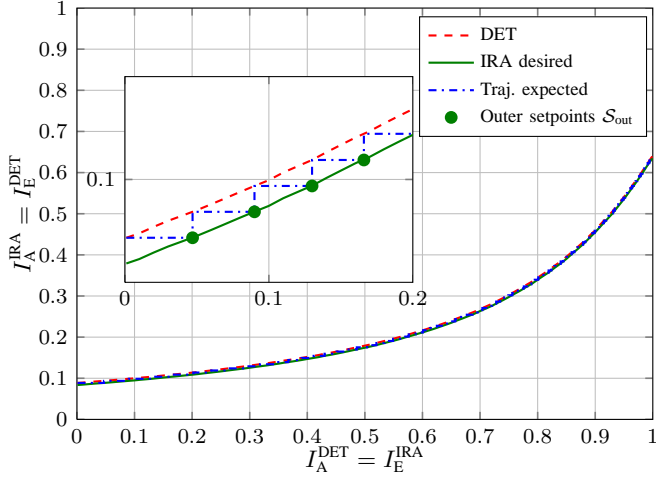


Fig. 5. Transfer characteristic of the detector at the working point (DET), the desired IRA code characteristic (IRA desired), the corresponding expected Trajectory (Traj. expected) and outer setpoints $s_{out,i} \in \mathcal{S}_{out}$.

$$\bar{I}_E^{IRA} := I_A^{DET} + \Delta \quad (8)$$

as depicted in Fig. 5. From the desired code characteristic, an expected trajectory through the EXIT-chart can be determined as also shown in the figure. Sampling the desired code characteristic

$$\bar{I}_E^{IRA} = T^{IRA,out}(I_A^{IRA}) \quad (9)$$

at discrete points leads to a set \mathcal{S}_{out} of outer setpoints

$$s_{out,i} = (\bar{I}_{A,i}^{IRA}, \bar{I}_{E,i}^{IRA}) \in \mathcal{S}_{out} \quad (10)$$

which the IRA code should fulfill. This means for a given a-priori information $\bar{I}_{A,i}^{IRA}$ which is fed from the detector to the IRA decoder, the decoder has to generate extrinsic information $\bar{I}_{E,i}^{IRA}$ in order to achieve the desired characteristic. Achieving more extrinsic information than $\bar{I}_{E,i}^{IRA}$ means a rate loss [11] while achieving less might close the tunnel between detector and decoder and, thus, prohibit successful detection. Clearly, the number of setpoints should be sufficiently large in order to approximate the desired characteristic. Hence, here one setpoint at every intersection between desired code characteristic and expected trajectory is calculated as depicted in Fig. 5.

2) *Inner code behaviour:* Having set the desired outer IRA code characteristic by outer setpoints, now the inner corresponding code characteristic has to be determined. That means, an irregular repetition code has to be found that for every outer setpoint $s_{out,i}$ the corresponding extrinsic information I_E^{IRA} is generated. For this, the set of outer setpoints \mathcal{S}_{out} is transformed into a set of inner setpoints \mathcal{S}_{in} .

First, the inner as well as the outer transfer characteristic of the convolutional decoder are evaluated at the input information $\bar{I}_{A,i}^{IRA}$ determined by $s_{out,i}$

$$I_E^{Acc} = T^{IRA,in}(I_A^{Acc}, \bar{I}_{A,i}^{IRA}) \quad (11)$$

$$I_E^{IRA} = T^{IRA,out}(I_A^{Acc}, \bar{I}_{A,i}^{IRA}). \quad (12)$$

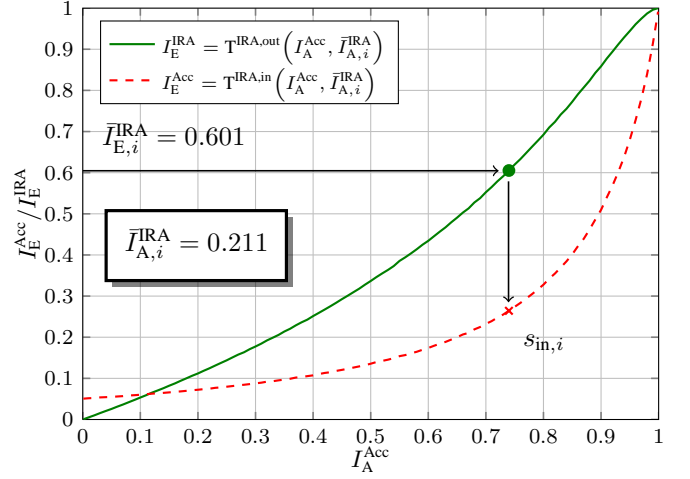


Fig. 6. Inner and outer transfer characteristics of the convolutional decoder \mathcal{D}_{Acc} at working point $\bar{I}_{A,i}^{IRA} = 0.211$. From the outer setpoint $s_{out,i} = (0.211, 0.601)$ (green dot) the corresponding inner setpoint $s_{in,i} = (0.211, 0.264)$ (red cross) is found.

Here, I_E^{Acc} is the extrinsic information generated by the convolutional decoder with respect to its information bits at the given $\bar{I}_{A,i}^{IRA}$ and I_E^{IRA} is the extrinsic information with respect to its codebits. From the outer setpoint $s_{out,i}$ the desired $\bar{I}_{E,i}^{IRA}$ is known which is indicated in Fig. 6 by a green dot. Mapping this point to the inner code characteristic

$$(\bar{I}_{A,i}^{IRA}, \bar{I}_{E,i}^{IRA}) \rightarrow \bar{I}_{E,i}^{Acc} \quad (13)$$

directly gives the corresponding inner setpoint

$$s_{in,i} = (\bar{I}_{A,i}^{Acc}, \bar{I}_{E,i}^{Acc}) \in \mathcal{S}_{in}. \quad (14)$$

This means, that the IRA code has to generate extrinsic information with respect to the information bits of $\bar{I}_{E,i}^{Acc}$ in order to produce extrinsic information of $\bar{I}_{E,i}^{IRA}$ with respect to the codebits, i.e., as feedback to the detector. Performing the above described procedure for every outer setpoint $s_{out,i} \in \mathcal{S}_{out}$ leads to the complete set of inner setpoints $s_{in,i} \in \mathcal{S}_{in}$. In Fig. 7 all inner setpoints are plotted. They now describe the inner characteristic the irregular repetition code as to be adapted to in order to achieve the outer desired characteristic (7). Thus, the problem to be solved is

$$[w_{\rho_{min}}, \dots, w_{\rho_{max}}] = \arg \min \{ I_E^{Rep} - \bar{I}_A^{Acc} \} \quad (15a)$$

$$\text{s.t.} \quad \sum_{\rho=\rho_{min}}^{\rho_{max}} w_{\rho} = 1 \quad (15b)$$

$$I_E^{Rep} \geq \bar{I}_A^{Acc}, \quad (15c)$$

Note that in contrast to the conventional approach no gap Δ between convolutional decoder and repetition decoder characteristic is required as decoding should intentionally get stuck at the setpoints. In Fig. 7 also the resulting repetition code and as comparison the repetition code from the conventional design approach is given. Interestingly, both repetition codes have a very similar transfer characteristic and differ only slightly in code rate.

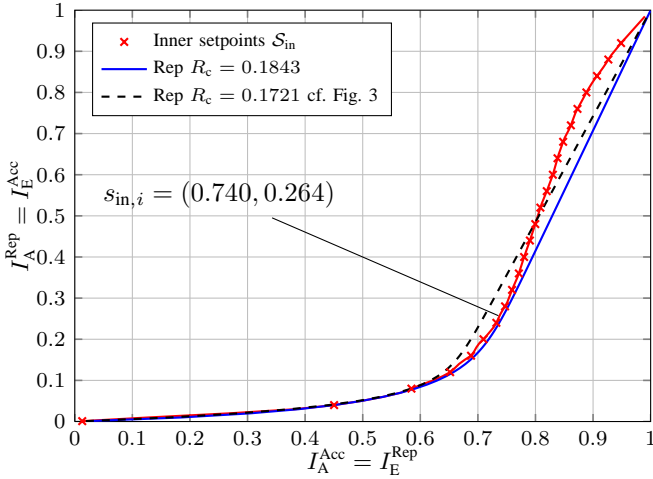


Fig. 7. The inner setpoints (red crosses) determine the overall characteristic the repetition code has to be adapted to. In contrast to Fig. 3 no gap between both curves is required.

In Fig. 8 again the transfer characteristic of the detector as well as the desired transfer characteristic of the IRA code are depicted. Furthermore, samples from the actual detection process obtained by Monte-Carlo simulations are shown. Each of these samples was obtained after the inner detection loop. As can be seen, the actual code characteristic follows the desired characteristic very closely. However, towards the end of the overall detection process, i.e. $I_A^{\text{IRA}} \gtrsim 0.25$, the code performance is better than desired. This is again due to the s-curve of the characteristic given by the inner setpoints as shown in Fig. 6, similar to the conventional design approach.

IV. CONCLUSION

In this paper, a novel setpoint-based design approach for Irregular Repeat Accumulate (IRA) Codes in iterative detection and decoding systems was presented. The goal behind this approach is to keep the IRA decoding structure consisting of convolutional decoder and repetition decoder intact, i.e. to consider it as an inner loop of the overall detection structure. This requires the joint adaptation of the repetition code to the detector as well as to the convolutional decoder which was achieved by formulating a desired IRA code characteristic and defining a set of corresponding outer setpoints. Mapping these setpoints to a set of inner setpoints finally allowed the optimization of the desired repetition code. It was shown, that this approach, although starting from a completely different viewpoint than the conventional strategy, leads to an irregular repetition code with a very similar transfer characteristic and code rate as the conventional approach. However, the presented approach has a slightly higher computational complexity than the conventional approach, since here usually more inner iterations are performed between convolutional decoder and repetition decoder as for the conventional approach between convolutional decoder and detector.

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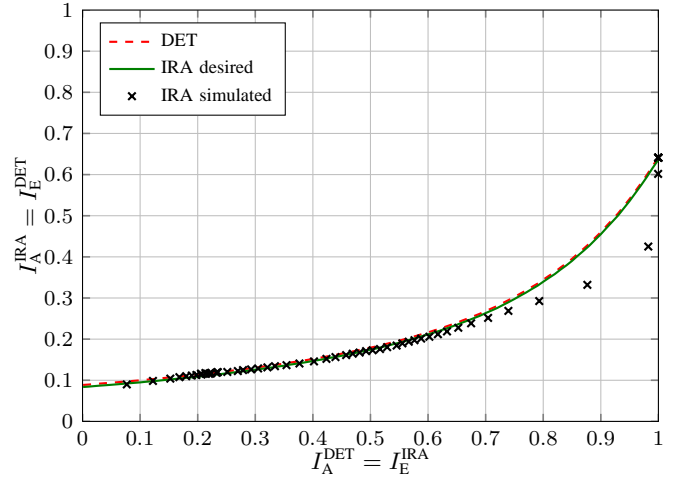


Fig. 8. Numerical results from Monte-Carlo simulations of the designed IRA code. IDMA multi-user system with $K = 16$ users and soft-RAKE detection over AWGN channels at $1/\sigma_n^2 = 5$ dB. $N_{\text{it,in}} = 20$ inner Iterations and $N_{\text{it,out}} = 50$ outer iterations.

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