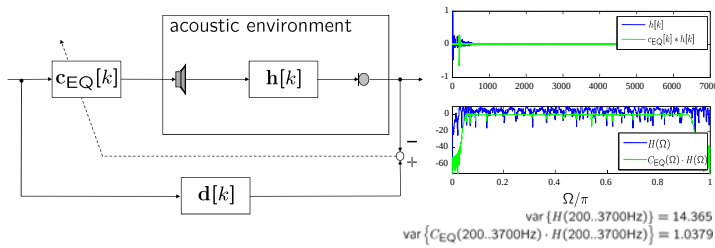


Motivation

- Listening Room Compensation (LRC) / Room Impulse Response Shaping can increase speech intelligibility.
- Since LRC devices are designed for fixed positions of loudspeaker and microphone spatial mismatch degrades performance.
- This contribution demonstrates the effects of spatial mismatch visually and acoustically.

Listening Room Compensation

- An equalizer precedes the acoustic channel
- Common design method: Least Squares Equalizer $c_{EQ} = H^+ d$
- Problem: Channel $h[k]$ is needed!



- The desired system $d[k]$ is approximated by the overall system of $c_{EQ}[k] * h[k]$

Room Impulse Response Shaping

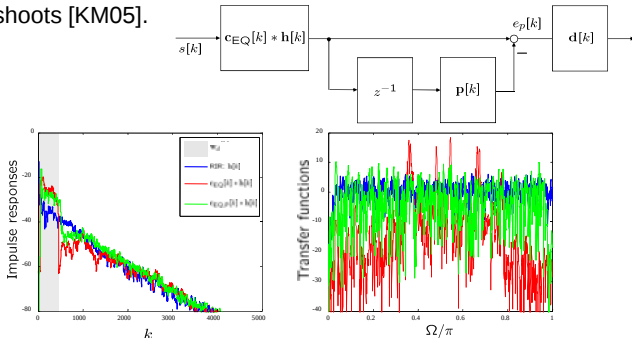
- The goal is not spectral flatness of the overall system but a concentration of the energy at a specified temporal envelope (desired area d_d).
- $d_d = \text{diag}\{w_d\} H c_{EQ}$
- $d_u = \text{diag}\{1 - w_d\} H c_{EQ}$
- Maximization of the energy of d_d while keeping the energy of d_u constant leads to the impulse response shortener after Melsa [MYR96, MMEJ03].

$$B_{BP} \cdot c_{EQ, \text{opt}} = A \cdot c_{EQ, \text{opt}} \cdot \lambda_{\max}$$

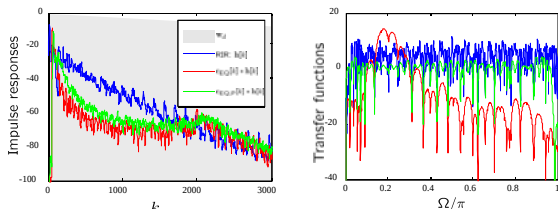
$$A = H^H \text{diag}\{w_{BP, d}\}^2 H$$

$$B_{BP} = H_{BP}^H \text{diag}\{w_{BP, d}\}^2 H_{BP}$$

- Problem: spectral peaks occur in overall transfer function!
- Post processing by a linear prediction filter can reduce the spectral overshoots [KM05].



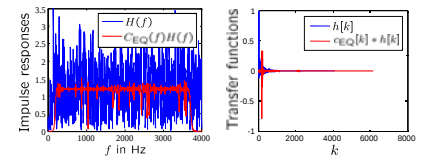
- For reducing the problem of late echoes the impulse response should better be *shaped* than shortened [KM05].
- This can be done by an exponential decreasing window.



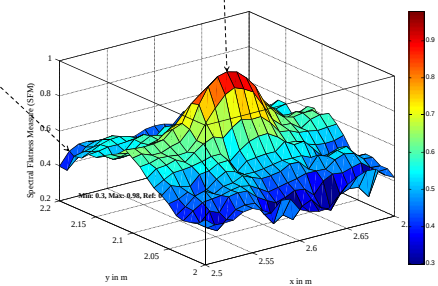
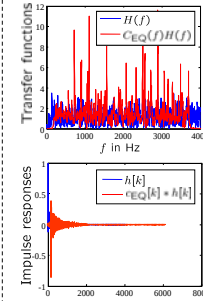
Spatial Sensitivity

- LRC devices are usually designed for fixed and a-priori known positions of source and microphone.
- If the assumptions of the spatial configuration are violated severe distortions may occur.

A known RIR leads to a good equalization.



For spatial mismatch severe distortions may occur!



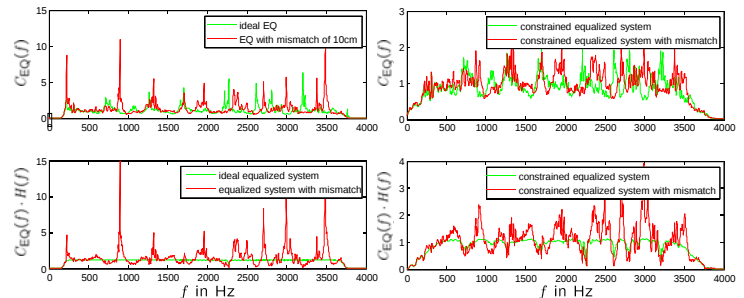
- Spectral Flatness Measure (SFM) for a LS-EQ, order 2048, $\tau_{60} = 200$ ms, position 3

Constrained LS-EQ design

- If an estimation error for the transfer function exist $H = \hat{H} + \tilde{H}$ the least squares EQ can be modified considering these errors.

$$c_{EQ} = (\hat{H}^T \hat{H} + \tilde{H}^T \tilde{H})^{-1} \hat{H}^T d$$

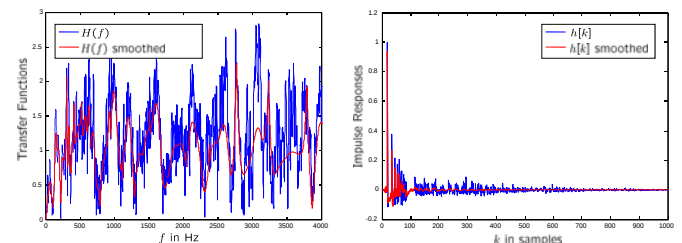
$$\approx \delta \cdot \|\hat{h}\|^2 I$$



- Constraining the least squares design enhances spatial robustness.
- Spectral peaks due to spatial mismatch can be strongly reduced.

Impulse Response Smoothing

- Complex Fractional Octave Smoothing as proposed in [HM00] is also capable to increase spatial robustness.



- RIR shaping and constrained LS-EQ design lead to spatially more robust LRC designs than Complex Smoothing.

Quality Assessment

- Subjective quality assessment is time consuming and expensive.
- Reliable and commonly accepted quality measurement (of enhancement) for dereverberation algorithms has yet to be found.

Objective Quality Measures for LRC

- Several measures can be found in the literature to evaluate dereverberation algorithms:

Measures based on the transfer function:

- Variance of logarithmic transfer function [Mou94]:

$$\sigma_{\mathcal{H}}^2 = \frac{1}{n_{\max} - n_{\min} + 1} \sum_{n=n_{\min}}^{n_{\max}} (20 \cdot \log_{10} |\mathcal{H}[n]| - \bar{\mathcal{H}}_{\text{dB}})^2$$

$$\bar{\mathcal{H}}_{\text{dB}} = \frac{1}{n_{\max} - n_{\min} + 1} \sum_{n=n_{\min}}^{n_{\max}} 20 \cdot \log_{10} |\mathcal{H}[n]|$$

$\mathcal{H}[n] = H[n]C_{\text{EQ}}[n]$: concatenated system of EQ and RTF
 n : discrete frequency index

$n_{\min}$: frequency index corresponding to $f = 200\text{Hz}$

$n_{\max}$: frequency index corresponding to $f = 3600\text{Hz}$

- Spectral Flatness Measure (SFM), [Joh88]

$$\text{SFM} = \frac{G_n}{A_n} = \frac{\sqrt[N]{\prod_{n=0}^{N-1} |\mathcal{H}[n]|^2}}{\frac{1}{N} \sum_{n=0}^{N-1} |\mathcal{H}[n]|^2}$$

$G[n]$: Geometric mean
 $A[n]$: Arithmetic mean

Measures based on the impulse response:

- “Deutlichkeit” (D50), [Kut00]

$k_{50} = 50\text{ms}/f_s$: discrete time index corresponding to a time of 50ms

- Clarity Index (CI), [Kut00]

$$\text{CI} = \frac{\sum_{k=0}^{k_{80}} (c_{\text{EQ}}[k] * h[k])^2[k]}{\sum_{k=k_{80}}^{L_h} (c_{\text{EQ}}[k] * h[k])^2[k]}$$

$k_{80} = 80\text{ms}/f_s$: discrete time index corresponding to a time of 80ms

- Central Time (CT), [Kut00]

$$\text{CT} = \frac{\sum_{k=0}^{L_h} k (c_{\text{EQ}}[k] * h[k])^2[k]}{\sum_{k=0}^{L_h} (c_{\text{EQ}}[k] * h[k])^2[k]}$$

- Direct-to-Reverberation-Ratio (DRR), [TS06]

$$\text{DRR}_{\text{dB}} = 10 \log_{10} \frac{(c_{\text{EQ}}[k_{h_{\max}}] * h[k_{h_{\max}}])^2}{\sum_{k \neq k_{h_{\max}}} (c_{\text{EQ}}[k] * h[k])^2}$$

$k_{h_{\max}}$: index of maximum of $h[k]$

Signal-based measures:

- Segmental Signal-to-Reverberation Ratio (SSRR), [NG05]

$$\text{SSRR}_{\text{dB}} = \frac{1}{K/L} \sum_{\ell=0}^{K/L-1} 10 \log_{10} \frac{\sum_{k=0}^{L-1} \tilde{y}[\ell L + k]^2}{\sum_{k=0}^{L-1} (\tilde{y}[\ell L + k] - y[\ell L + k])^2}$$

K : signal length

L : block length

ℓ : block index

$\tilde{y}[k]$: signal after desired system $d[k]$

$y[k]$: microphone signal

- Bark Spectral Distortion (BSD), [Yan99]

$$\text{BSD} = \frac{\frac{1}{K/L} \sum_{\ell=0}^{K/L-1} \sum_{i=1}^Q [L_{\tilde{y}}^{(\ell)}(i) - L_y^{(\ell)}(i)]^2}{\frac{1}{K/L} \sum_{\ell=0}^{K/L-1} \sum_{i=1}^Q [L_{\tilde{y}}^{(\ell)}(i)]^2}$$

Q : No. of critical bands

i : No. of critical band

$L_{\tilde{y}}^{(\ell)}$: Bark spectrum of frame ℓ

$L_y^{(\ell)}$: Bark spectrum of frame ℓ

- Cepstral Distance (CD), [Yan99]

$$\text{CD} = \frac{1}{K/L} \sum_{\ell=1}^{K/L-1} \left\{ \frac{10}{\ln 10} \sqrt{[C_{\text{LP}}^{(\tilde{y})}(1, \ell) - C_{\text{LP}}^{(y)}(1, \ell)]^2 + 2 \sum_{i=2}^m [C_{\text{LP}}^{(\tilde{y})}(i, \ell) - C_{\text{LP}}^{(y)}(i, \ell)]^2} \right\}$$

$$C_{\text{LP}}^{(x)}(i) = a_i + \frac{1}{i} \sum_{j=1}^{i-1} (i-j) \cdot C_{\text{LP}}^{(x)}(i-j) \cdot a_j \quad \text{for } i = 1, 2, 3, \dots$$

$$a = -R_{xx}^{-1} r_{xx}$$

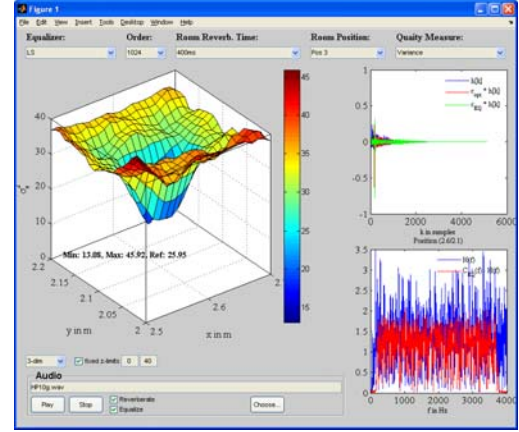
$C_{\text{LP}}^{(y)}$: Cepstral Coefficients for signal y

i : Cepstral Coefficient index

a : Coefficients of Linear Predictor

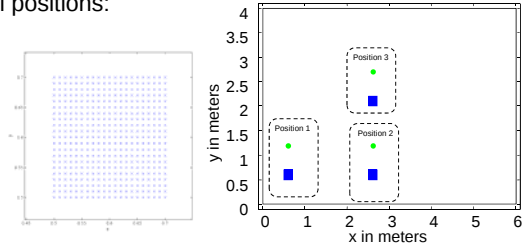
MATLAB® Demo

- The different LRC schemes can be compared by means of various objective measures (see left column). Furthermore a subjective quality assessment is possible by applying the precomputed equalizers to a given sound-file and by listening to the equalized sound-file acoustically.



- Possible EQ designs: LS-EQ, Constrained LS-EQ, RIR smoothing, RIR shaping
- Possible EQ orders (@8kHz): 128, 256, 512, 1024, 2048
- Possible room reverberation times: 50ms, 100ms, 200ms, 400ms, 800ms, 1200ms

- Possible spatial positions:



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